#### Advanced Topics in Communication Networks Programming Network Data Planes



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#### Last week on

#### Advanced Topics in Communication Networks



Probabilistic data structures like Bloom Filters help to trade resources with accuracy





#### Bloom Filters take a fixed number of operations,

but hash collisions can cause false positives.





Bloom Filters take a fixed number of operations,

#### but hash collisions can cause false positives





#### A bloom filter is a streaming algorithm answering specific questions approximately.



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#### answering specific questions approximately.

#### Is X in the stream? What is in the stream?<sup>Invertible Bloom Filter</sup>

A bloom filter is a streaming algorithm **answering specific questions approximately**.

Is X in the stream? What is in the stream?<sup>Invertible Bloom Filter</sup>

#### What about other questions?

#### Today we'll talk about: important questions,

how 'sketches' answer them,

and limitations of 'sketches'

my master thesis :)

*Is a certain flow in the stream? Bloom Filter* 

What flows are in the stream? Invertible Bloom Filter, HyperLogLog Sketch, ...

How frequent does an flow appear? Count Sketch, CountMin Sketch, ...

What are the most frequent elements? Count/CountMin + Heap, ...

How many flows belong to a certain subnet? SketchLearn SigComm '18 In networking, we talk about **flows of packets**, but these questions apply to other domains as well, e.g. **search engines and databases**. *Is a certain flow in the stream? Bloom Filter* 

What flows are in the stream? Invertible Bloom Filter, HyperLogLog Sketch, ...

How frequently does an flow appear? Count Sketch, CountMin Sketch, ...

What are the most frequent elements? Count/CountMin + Heap, ...

How many flows belong to a certain subnet? SketchLearn SIGCOMM '18 We are going to look at **frequencies**,

i.e. how often an element occurs in a data stream.



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i.e. how often an element occurs in a data stream.



distinct flows

In the worst case, an algorithm providing exact frequencies requires linear space. In the worst case, an algorithm providing **exact frequencies** requires **linear space**.



In the worst case, an algorithm providing **exact frequencies** requires **linear space**.



In the worst case, an algorithm providing **exact frequencies** requires **linear space**.



#### Probabilistic datastructures can help again!

#### **Bloom Filters**

quickly "filter" only those elements that might be in the set Save space by allowing false positives.

#### Probabilistic datastructures can help again!

#### **Bloom Filters**

*quickly "filter" only those elements that might be in the set Save space by allowing* 

false positives.

#### Sketches

provide a approximate frequencies of elemetns in a data stream. Save space by allowing mis-counting.

#### Today we'll talk about: important questions,

#### how 'sketches' answer them,

limitations of 'sketches',

and my master thesis :)

# A **CountMin sketch** uses the same principles as a counting bloom filter, but is **designed** to have **provable L1 error bounds** for frequency queries.

#### A **CountMin sketch** uses the same principles as a counting bloom filter, but is **designed** to have **provable L1 error bounds** for frequency queries.

Notation reminder:

vector of frequencies (counts)

of all **distinct elements x**,

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \end{bmatrix}$$

#### A **CountMin sketch** uses the same principles as a counting bloom filter, but is **designed** to have **provable L1 error bounds** for frequency queries.

## $\Pr \begin{bmatrix} \hat{x}_i - x_i \geq \varepsilon \|x\|_1 \end{bmatrix} \leq \delta \\ \text{estimated} \quad \text{true} \quad \text{sum of} \\ \text{frequency} \quad \text{frequency} \quad \text{frequencies} \\ \end{array}$

The estimation error exceeds  $\varepsilon \|x\|_1$ with a probability smaller than  $\delta$ 



The estimation error exceeds  $\varepsilon \| \mathbf{x} \|_{1}$ with a probability smaller than  $\delta$ 



Let  $\varepsilon = 0.01$ ,  $\delta = 0.05$ ,  $||\mathbf{x}||_1 = 10000$ The probability for **any estimate** to be off by **more than 100** is **less than 5%** (after counting 10000 elements)

#### A **CountMin sketch** uses the same principles as a counting bloom filter, but is **designed** to have **provable L1 error bounds** for frequency queries.

#### A **CountMin** Sketch uses multiple arrays and hashes.





#### Hash collisions cause over-counting.



#### Returning the **minimum value** minimizes the error.



#### A **CountMin sketch** uses the same principles as a counting bloom filter, but is designed to have

**provable L1 error bounds** for frequency queries.

 $Pr\left[ \hat{x}_{i} - x_{i} \geq \varepsilon \|\mathbf{x}\|_{1} \right] \leq \delta$ 

true

estimated frequency frequency

sum of frequencies

## Understanding the error bounds allows **dimensioning** the sketch optimally.

**Error Bounds** 

per hash/array

**Error Bounds** 

for the minimum

**Optimal Size** 

#### **Error Bounds**

per hash/array

### $\widehat{x}_i = \min_{h \in h_1 \dots h_d} \widehat{x}_i^h$

estimated frequency estimate for specific hash

**Error Bounds** 

for the minimum

**Optimal Size** 



 $\widehat{x}_i^h$ 

estimate for

specific hash
## The error bounds can be derived with Markov's Inequality



## The error bounds can be derived with **Markov's Inequality**



**Error Bounds** for the minimum

**Optimal Size** 

$$\Pr\left[\widehat{x}_{i}^{h}-x_{i} \ge c \cdot E\left[\widehat{x}_{i}^{h}-x_{i}\right]\right] \le \frac{1}{c}$$

wikipedia.org/wiki/Markov's\_inequality



per hash/array

$$\Pr\left[\hat{x}_{i}^{h}-x_{i}\geq c\cdot E\left[\hat{x}_{i}^{h}-x_{i}\right]\right]\leq\frac{1}{c}$$

$$\hat{x}_{i}^{h} = x_{i} + \sum_{x_{j} \neq x_{i}} x_{j} \mathbf{1}_{h} (x_{i}, x_{j})$$

**Error Bounds** for the minimum

true frequency over-counting from hash collisions



per hash/array

**Error Bounds** for the minimum

**Optimal Size** 

$$\Pr\left[\hat{x}_{i}^{h}-x_{i} \ge c \cdot E\left[\hat{x}_{i}^{h}-x_{i}\right]\right] \le \frac{1}{c}$$

$$\widehat{x}_{i}^{h} = x_{i} + \sum_{x_{j} \neq x_{i}} x_{j} 1_{h}(x_{i}, x_{j})$$

hash collision

$$= \begin{cases} 1, & \text{if } h(x_i) = h(x_j) \\ 0, & \text{otherwise} \end{cases}$$

#### **Error Bounds**

per hash/array

**Optimal Size** 

 $\Pr\left[\hat{x}_{i}^{h}-x_{i} \ge c \cdot E\left[\hat{x}_{i}^{h}-x_{i}\right]\right] \le \frac{1}{c}$ 

$$\widehat{\mathbf{x}}_i^h - \mathbf{x}_i = \sum_{x_i \neq x_i} x_j \mathbf{1}_h(x_i, x_j)$$

estimation error over-counting from hash collisions



**Error Bounds** for the minimum

$$\Pr\left[\widehat{x}_{i}^{h}-x_{i} \ge c \cdot E\left[\widehat{x}_{i}^{h}-x_{i}\right]\right] \le \frac{1}{c}$$

$$\widehat{x}_{i}^{h} - x_{i} = \sum_{x_{j} \neq x_{i}} x_{j} 1_{h} (x_{i}, x_{j})$$

$$E\left[\widehat{x}_{i}^{h}-x_{i}\right] = E\left[\sum_{x_{j}\neq x_{i}} x_{j} 1_{h}(x_{i}, x_{j})\right]$$





$$\Pr\left[\hat{x}_{i}^{h}-x_{i} \ge c \cdot E\left[\hat{x}_{i}^{h}-x_{i}\right]\right] \le \frac{1}{c}$$

$$\hat{x}_{i}^{h} - x_{i} = \sum_{x_{j} \neq x_{i}} x_{j} 1_{h} (x_{i}, x_{j})$$

 $E\left[\widehat{x}_{i}^{h}-x_{i}\right] = \sum_{x_{j}\neq x_{i}} x_{j} E\left[1_{h}\left(x_{i}, x_{j}\right)\right]$ 



wikipedia.org/wiki/Universal\_hashing



$$\Pr\left[\widehat{x}_{i}^{h}-x_{i} \ge c \cdot E\left[\widehat{x}_{i}^{h}-x_{i}\right]\right] \le \frac{1}{c}$$

$$\hat{x}_{i}^{h} - x_{i} = \sum_{x_{j} \neq x_{i}} x_{j} \mathbf{1}_{h} (x_{i}, x_{j})$$

$$\mathbf{E}\left[\widehat{x}_{i}^{h}-x_{i}\right] \leq \sum_{x_{j}\neq x_{i}} x_{j} \frac{1}{w}$$



**Error Bounds** for the minimum

$$\Pr\left[\hat{x}_{i}^{h}-x_{i}\geq c\cdot E\left[\hat{x}_{i}^{h}-x_{i}\right]\right]\leq\frac{1}{c}$$

$$\widehat{x}_{i}^{h} - x_{i} = \sum_{x_{j} \neq x_{i}} x_{j} 1_{h} (x_{i}, x_{j})$$

$$\mathbf{E}\left[\widehat{x}_{i}^{h}-x_{i}\right] \leq \sum_{x_{j}\neq x_{i}} x_{j} \frac{1}{w} \leq \sum_{x_{j}} x_{j} \frac{1}{w}$$



**Error Bounds** for the minimum

$$\Pr\left[\hat{x}_{i}^{h}-x_{i}\geq c\cdot E\left[\hat{x}_{i}^{h}-x_{i}\right]\right]\leq\frac{1}{c}$$

$$\widehat{x}_{i}^{h} - x_{i} = \sum_{x_{j} \neq x_{i}} x_{j} 1_{h} (x_{i}, x_{j})$$

$$\mathbb{E}\left[\widehat{x}_{i}^{h}-x_{i}\right] \leq \sum_{x_{j}\neq x_{i}} x_{j} \frac{1}{w} \leq \left\|\boldsymbol{x}\right\|_{1} \frac{1}{w}$$

#### **Error Bounds**

per hash/array

**Error Bounds** for the minimum

$$\Pr\left[\hat{x}_{i}^{h} - x_{i} \ge c \cdot \underbrace{E\left[\hat{x}_{i}^{h} - x_{i}\right]}_{\leq \frac{1}{w} \|x\|_{1}}\right] \le \frac{1}{c}$$

#### **Error Bounds**

per hash/array

**Error Bounds** for the minimum

$$\Pr\left[\widehat{x}_{i}^{h}-x_{i}\geq\frac{C}{W}\left\|\boldsymbol{x}\right\|_{1}\right]\leq\frac{1}{C}$$



per hash/array

**Error Bounds** for the minimum

$$\Pr\left[\hat{x}_{i}^{h} - x_{i} \ge \underbrace{\varepsilon}_{w}^{h} \| \mathbf{x} \|_{1}\right] \le \underbrace{\delta}_{\frac{1}{c}}^{h}$$

**Error Bounds** for the minimum

 $\Pr\left[\widehat{x}_{i}^{h} - x_{i} \ge \underbrace{\varepsilon}_{w}^{h} ||\mathbf{x}||_{1}\right] \le \underbrace{\delta}_{\frac{1}{c}}^{h}$ 

### The **estimate for each hash** has a well defined **L1 error bound**.



**Error Bounds** for the minimum

**Optimal Size** 

$$\Pr\left[\hat{x}_{i}^{h} - x_{i} \ge \underbrace{\varepsilon}_{w}^{h} ||\mathbf{x}||_{1}\right] \le \underbrace{\delta}_{\frac{1}{c}}^{h}$$

The estimate for each hash has a well defined L1 error bound.

#### What about the minimum?

$$Pr\left[\widehat{\boldsymbol{x}}_{i}-\boldsymbol{x}_{i}\geq\frac{C}{W}\|\boldsymbol{x}\|_{1}\right] \leq ?$$

**Error Bounds** for the minimum

**Error Bounds** for the minimum

$$Pr\left[\min_{\substack{h \in h_1..h_d \\ \hat{x}_i}} \hat{x}_i^h - x_i \ge \frac{C}{W} \|x\|_1\right] \leq ?$$

#### Multiple hash functions work like independent trials.





$$\Pr\left[\min_{\substack{h \in h_1..h_d \\ \hat{x}_i}} \widehat{x}_i^h - x_i \ge \frac{C}{W} \|\mathbf{x}\|_1\right] \leq ?$$

$$\prod_{a \in h_1 \dots h_d} \Pr\left[\widehat{x}_i^h - x_i \ge \frac{c}{w} \|x\|_1\right] \leq ?$$

$$\leq \frac{1}{c}$$
error bound per hash



$$\Pr\left[\min_{\substack{h \in h_1...h_d \\ \hat{x}_i}} \widehat{x}_i^h - x_i \ge \frac{C}{W} \|x\|_1\right] \leq ?$$

$$\prod_{a \in h_1 \dots h_d} \Pr\left[\widehat{x}_i^h - x_i \ge \frac{c}{w} \|x\|_1\right] \leq \frac{1}{c^d}$$

$$Pr\left[\min_{\substack{h \in h_1..h_d \\ \hat{x}_i}} \widehat{x}_i^h - x_i \ge \frac{c}{w} \|x\|_1\right] \le \frac{1}{c^d}$$

**Error Bounds** for the minimum

**Optimal Size** 

1

$$Pr\left[\hat{x}_{i} - x_{i} \ge \frac{c}{w} \|\boldsymbol{x}\|_{1}\right] \le \frac{1}{c^{d}}$$

**Error Bounds** for the minimum

**Error Bounds** for the minimum

**Optimal Size** 

$$Pr\left[\hat{x}_{i} - x_{i} \ge \underbrace{\varepsilon}_{w} ||\mathbf{x}||_{1}\right] \le \underbrace{\delta}_{\frac{1}{c^{d}}}$$

We have proven the error bounds! But what about the constant c? For **every c**, there is a pair (d, w) achieving the error bound and confidence  $(\varepsilon, \delta)$ .



### Choosing c=e **minimizes** the total **number of counters**.



#### A CountMin sketch recipe





$$w = \left| \frac{e}{\varepsilon} \right|$$
 (hash range)  
$$d = \left[ \ln \frac{1}{\delta} \right]$$
 (#hashes)

requires the **minimum number of counters** s.t. the CountMin Sketch can guarantee that

 $\widehat{x}_{i} - x_{i} \ge \varepsilon \| \mathbf{x} \|_{1}$ with a probability less than  $\delta$ 

# A **CountMin sketch** uses the same principles as a counting bloom filter, but is **designed** to have **provable L1 error bounds** for frequency queries.

A **CountMin sketch** uses the same principles as a counting bloom filter, but is **designed** to have **provable L1 error bounds** for frequency queries.

**CountMin** sketch recipe

**Choose**  $d = \left[ \ln \frac{1}{\delta} \right], w = \left[ \frac{e}{\varepsilon} \right]$ **Then**  $\hat{x}_i - x_i \ge \varepsilon \| \mathbf{x} \|_1$  with a probability less than  $\delta$ 

# A **CountMin sketch** uses the same principles as a counting bloom filter, but is **designed** to have **provable L1 error bounds** for frequency queries.

→ only one design out of many!

A Count sketch uses the same principles as a counting bloom filter, but is designed to have
provable L2 error bounds for frequency queries.

#### <u>CountMin sketch</u>

 $h_1, ..., h_d: U \rightarrow \{1, ..., w\}$ 

**COUNT**  $X_{i:}$ for h in h<sub>1</sub>, ..., h<sub>d</sub>: Reg<sub>h</sub>[h(x<sub>i</sub>)] + 1

#### QUERY $x_i$ :

return min<sub>h in h1, ..., hd</sub>(
 Reg<sub>h</sub>[h(x<sub>i</sub>)]
)

#### <u>CountMin sketch</u>

 $h_1, ..., h_d: U \rightarrow \{1, ..., w\}$ 

**COUNT**  $X_{i:}$ for h in  $h_1$ , ...,  $h_d$ : Reg<sub>h</sub>[h( $x_i$ )] + 1

#### QUERY $X_i$ :

return min<sub>h in h1, ..., hd</sub>(
 Reg<sub>h</sub>[h(x<sub>i</sub>)]
)

#### Count sketch

 $h_1, ..., h_d: U → \{1, ..., w\}$ g: U → {+1, -1}

COUNT  $X_{i:}$ for h in  $h_1$ , ...,  $h_d$ : Reg<sub>h</sub>[h( $x_i$ )] + g( $x_i$ )

QUERY  $x_i$ : return median<sub>h in h1, ..., hd</sub> (  $Reg_h[h(x_i)] * g(x_i)$ )

CountMin sketch recipe

**Choose**  $d = \left[ \ln \frac{1}{\delta} \right], w = \left[ \frac{e}{\varepsilon} \right]$ 

**Then**  $\hat{x}_i - x_i \ge \varepsilon \|\mathbf{x}\|_1$  with a probability less than  $\delta$ 

CountMin sketch recipe

**Choose**  $d = \left[ \ln \frac{1}{\delta} \right], w = \left[ \frac{e}{\varepsilon} \right]$ 

**Then**  $\hat{x}_i - x_i \ge \varepsilon \|\mathbf{x}\|_1$  with a probability less than  $\delta$ 

Count sketch recipe

**Choose** 
$$d = \left[ \ln \frac{1}{\delta} \right], w = \left[ \frac{e}{\epsilon^2} \right]$$

**Then**  $\hat{x}_i - x_i \ge \varepsilon \|\mathbf{x}\|_2$  with a probability less than  $\delta$
# Sketches are the new black

## ...and many more!

## OpenSketch

**NSDI '13** 

## [source]

#### Software Defined Traffic Measurement with OpenSketch

Minlan Yu<sup>†</sup> Minlan Yu<sup>†</sup> Lavanya Jose<sup>\*</sup> Rui Miao<sup>†</sup> <sup>†</sup> University of Southern California <sup>\*</sup> Princeton University

OpenSetch provides a measurement iterary that auto-matically configures the pipeline and allocates resources for different measurement tasks. Our evaluations of real-world apaket traces, our prototype on NetFPGA, and the implementation of *five* measurement tasks on top of OpenStetch, demonstrate that OpenStetch is general, ef-ficient and easily programmable.

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The second start programmable. A second start programmable in a course of the second start provide a start pro

## UnivMon

SIGCOMM '16

## [source]

## One Sketch to Rule Them All: Rethinking Network Flow Monitoring with UnivMon

## Zaoxing Liu<sup>1</sup>, Antonis Manousis<sup>+</sup>, Gregory Vorsanger<sup>1</sup>, Vyas Sekar<sup>+</sup>, Vladimir Braverman<sup>1</sup> <sup>1</sup> Johns Hopkins University <sup>+</sup> Carnegie Mellon University

1 Introduction

#### ABSTRACT

ABSTRACT Network management requires accurate estimates of mérics for many applications including traffic engineering (e.g., ing traffic and traffic engineering (e.g., ing traffic engineering (e.g., estimates) of main particular estimates given router CPU and memory con-trains is a challenging problem. Existing approaches fail pupose approaches such as signific, and (e.g., estimates) pupose approaches such as signific, and (e.g., estimates) fupose approaches such as signific, and (e.g., estimates) fupose approaches such as signific, and (e.g., estimates) approaches approaches and as a signification of pupose approaches such as signific, and (e.g., estimates) fupose approaches such as signific, and (e.g., estimates) fupose approaches and a signification is should be both estimates (estimates) and approfilms. This paper presents of proper approaches approaches and the signification of the control particular signification of the control particular of the control particular signification of the control particular of the proper application-include training and regin theorem and in the control particular signification of the control particular of the control particular of the signification of the control particular of the control pa lutions across a range of monitoring tasks.

## CCS Concepts

 $\bullet Networks \rightarrow Network \ monitoring; \ Network \ measurement:$ 

Keywords Flow Monitoring, Sketching, Streaming Algorithms From Monitoring, Stetching, Streaming Augoritamis Permission to make fightal or hard coips of all or part of this work for personal or classroom use in granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies hear this notice and the full citation on the first page. Copyrights for components of this work owned by others that ACM must be bonced. Abstracting with crudit is pre-mitted. To copy otherwise, or republish, to post on servers or to redistribute to lists, requires projectic permission andler a face. Rangeet permission from

permissions of acm.org. SIGCOMM '16, August 22–26, 2016, Florianopolis, Brazil © 2016 ACM. ISBN 978-1-4503-4193-6/1608...\$15.00 lldx doi org/10 1145/2934872 2934906

skerching or streaming algorithms. Here, custom online al-porithms and data structures are designed for specific met-rics of interest that can yield provable resource-accuracy trade-offs (e.g., 117, 12, 02, 13, 05, 38, 43). While the body of work in data streaming and sketching has made significant contributions, we argue that this trajec-tory of crafting special-purpose algorithms is untenable in mentalis significant investment in algorithm design and hard-ware support for new metrics of interest. While recent toosh like OpenStetch (71 and SCREMA [14] provide tharasits to reduce the implementation effort and offer efficient resource allocation, they do not address the fundamental need to de-sign and operate new custom sketches for each task. Fur-hermore, at any given point in time the data plane resources have to be committed (a priori) to a specific set of metrics to monitor and will have fundamental blind spots for other metrics that are not currently being tracked. Beally, we want a monitoring framework that offers both generality by delaying the binding to specific applications of interest but at he same time provides the required *fidelity* for estimating these metrics. Achieving generality and high fidelity simulancously has been an elusive goal both in the-ory [33] (Question 24) as well as in practice [45].

Network management is multi-faceted and encompasses a range of tasks including traffic engineering [11, 32], attack and anomaly detection [49], and forensic analysis [46]. Each

and anomaly detection [49], and forensis analysis [46]. Each such management task requires accurate and innely stati-tics on different application-level metrics of interest; e.g., the flow size distribution [37]. heavy hitters [10], entropy mea-sures [38, 50], or detecting changes in traffic patterns [44]. At a high level, there are two classes of techniques to esti-mate these metrics of interest. The first class of approaches relies on generic flow monitoring, typically with some form of packet sampling (e.g., NetFlow [25]). While generic flow monitoring is good for coarse-grained visibility, prior work has shown that it provides low accuracy for more fine-grained metrics [30, 13, 43]. These well-known limitations of sam-pling motivated an alternative class of techniques based on sterking or stramming algorithms. Here, custom online al-gorithms and data structures are designed for specific met-rics of interest that can yield provable resource-accuracy trade-

(b) (5) (Question 24) as well as in practice [5]. In this paper, we present the UnivMon (short for Univer-sal Monitoring) framework that can simultaneously achieve both generality and high fidelity across a broad spectrum of monitoring tasks [31, 36, 38, 51]. UnivMon builds on and

## SketchLearn

## SIGCOMM '18

## [source]

## SketchLearn: Relieving User Burdens in Approximate **Measurement with Automated Statistical Inference**

#### Qun Huang<sup>†</sup>, Patrick P. C. Lee<sup>‡</sup>, and Yungang Bao<sup>†</sup>

<sup>†</sup>State Key Lab of Computer Architecture, Institute of Computing Technology, Chinese Academy of Sciences <sup>‡</sup>Department of Computer Science and Engineering, The Chinese University of Hong Kong

ABSTRACT Network measurement is challenged to fulfill stringert re-source requirements in the face of massive network traffic. While approximate measurement can trade accuracy. A how the her particulation of the face of the string of the s Such user burdens are caused by how existing approximate measurement approaches inherently deal with resource con-flicts when tracking massive network traffic with limited resources. In particular, they tightly couple resource config-urations with accuracy parameters, so as to provision suffi-cient resources to bound the measurement terrors. We design SketchLaern, a novel sketch-based measurement framework that resolves resource conflicts by Lenning their statistical properties to eliminate conflicting traffic components. We prototype SketchLaern on QenetVswich and P4, and our testbed experiments and stress-test simulation show that SketchLaern accurately and numerically monitors varian testore experiments and stress test simulation show that SketchLearn accurately and automatically monitors various traffic statistics and effectively supports network-wide mea-surement with limited resources.

#### CCS CONCEPTS Networks → Network measurement;

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KEYWORDS

#### Sketch; Network measurement

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and sketch-based approaches [18, 33, 40, 42, 58], which we collectively refer to as approximate measurement approaches. Their idea is to construct compact sub-linear data structures to record traffic statistics, backed by theoretical guarantees on how to achieve accurate measurement while limited re-sources. Approximate measurement has formed building blocks in may state-of-the-sut network-wide measurement systems (e.g., [32, 48, 55, 60, 62, 67]), and is also adopted in production data centers [31, 64]. Although theoretically sound, existing approximate mea-surement approaches are inconversient for use. In such ap-proaches, massive network traffic competes for the limited resources, thereby introducing measurement Torms due to *resource conflicts* (e.g., multiple flows are mapped to the same counter in sketh-based measurement). To miligate errors, a asion to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear thin notice and the full citation on the first page. Copyrights for components of this work owned by others than ACM must be honored. Abstracting with credit is permitted. To copy otherwise, or republish, ho post on servers or to redistribute to lists, requires prior specific permission and/or a fee. Request resource conflicts (e.g., multiple lows are mapped to the same counter in sketch-based measurement). To miligate errors, sufficient resources must be provisioned in approximate mea-surement based on its theoretical guarantees. Thus, there exists a tight binding between resource configurations and accuracy parameters. Such tight binding leads to several prac-tical limitations (es §2.2 for details): (i) administrators need

1 INTRODUCTION Network measurement is indispensable to modern network management in clouds and data centers. Administrators mea-ure a variety of traffic statistics, such as per-dlow frequency, to infer the key behaviors or any unexpected patterns in op-erational networks. They use the measured traffic statistics to form the basis of management operations such as traffic regimeering performance diagons, and intrusis taisatist to form the basis of management operations are also per-tion. Intercurately, measuring traffic natistics is more trained interconstructions are surrented remains networks work dealwavent. Everoption neurostructuring networks

in the face of massive network traffic and large-scale net-work deployment. Error-free measurement requires per-flow tracking [15], yet today's data center networks can have thousands of concurrent flows in a very small period from 50ms [2] down to even 5ms [56]. This would require tremo-baus resources for performing per-flow tracking. In view of the resource constraints, many approaches in the literature leverage approximation techniques to track be-tween resource usage and measurement accuracy. Examples include sampling [9, 37, 64], top-6 conting [5, 43, 44, 64], and stetch-based approaches [18, 33, 40, 42, 5], which we collectively refer to a a commonime renormer measuremeters.

# Sketches are the new black

# **OpenSketch NSDI '13**

## [source]

#### Software Defined Traffic Measurement with OpenSketch

Minlan Yu<sup>†</sup> Minlan Yu<sup>†</sup> Lavanya Jose<sup>\*</sup> Rui Miao<sup>†</sup> <sup>†</sup> University of Southern California <sup>\*</sup> Princeton University

OpenSketch provides a measurement library that auto-matically configures the pipeline and allocates resources for different measurement tasks. Our evaluations of real-world packet traces, our prototype on NetPFOA, and the implementation of *five* measurement tasks on top of OpenSketch, demonstrate that OpenSketch is general, ef-ficient and easily programmable.

Abstract Most network management tasks in software-defined measurement architecture. The key control White many efforts have been focused on the control. White many efforts have been focused on the measurement API is to strike a careful balance between parket of the second s may need to focus on small flows (e.g., anomaly detec-tion) and thus requiring another way of changing Net-Flow. Instead, we should provide more customized and dynamic measurement data collection defined by the soft-ware written by operators based on the measurement re-quirements; and provide guarantees on the measurement accuracy.

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ABSTRACT Notor management requires accurate estimates of met-fix for many epplications including traffic: engineering (e.g., engineering) and engineering engineering engineering substrates and engineering engineering engineering substrates and engineering engi lutions across a range of monitoring tasks.

## CCS Concepts

## $\bullet Networks \rightarrow Network$ monitoring; Network measurement:

Keywords Flow Monitoring, Sketching, Streaming Algorithms From Monitoring, Stetching, Streaming Augoritamis Permission to make digilat or hard coips of all or part of this work for personal or classroom use in granted without fee provided that coipsis are not made or distributed for profit or commercial advantage and that coipsis host mits notice and the full citation on the first page. Copyrights for composents of this work owned by dotten that ACM must be honored. Abstracting with crudit is pre-mitted. To copy otherwise, or rupblish, to post on servers or to redistribute to lists, requires profit specific pennistion andles a face. Request permission from

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1 Introduction Network management is multi-faceted and encompasses a range of tasks including traffic engineering [11, 32], attack and anomaly detection [49], and forensic analysis [46]. Each and anomaly detection [49], and forensis analysis [46]. Each such management task requires accurate and innely stati-tics on different application-level metrics of interest; e.g., the flow size distribution [37], hosey hitters [10], entropy mea-sures [38, 50], or detecting changes in traffic patterns [44]. At a high hevel, there are two classes of techniques to esti-mate these metrics of interest. The first class of approaches relies on generic flow monitoring, typically with some form of packet sampling (e.g., NetFlow [25]). While generic flow monitoring is good for coarse-grained visibility, prior work has shown that it provides low accuracy for more fine-grained metrics [30, 31, 43]. These well-known limitations of sam-pling motivated an alternative class of techniques based on alterhing or arguentime and the structures are designed for specific met-rics of interest that can yield provable resource-accuracy trade-

skerching or streaming algorithms. Here, custom online al-porithms and data structures are designed for specific met-rics of interest that can yield provable resource-accuracy trade-offs (e.g., 117, 12, 02, 13, 05, 38, 43). While the body of work in data streaming and sketching has made significant contributions, we argue that this trajec-tory of crafting special-purpose algorithms is untenable in mentalis significant investment in algorithm design and hard-ware support for new metrics of interest. While recent toosh like OpenStetch (71 and SCREMA [14] provide tharasits to reduce the implementation effort and offer efficient resource allocation, they do not address the fundamental need to de-sign and operate new custom sketches for each task. Fur-hermore, at any given point in time the data plane resources have to be committed (a priori) to a specific set of metrics to monitor and will have fundamental blind spots for other metrics that are not currently being tracked. Beally, we want a monitoring framework that offers both generality by delaying the binding to specific applications of interest but at he same time provides the required *fidelity* for estimating these metrics. Achieving generality and high fidelity simulancously has been an elusive goal both in the-ory [33] (Question 24) as well as in practice [45].

(b) (5) (Question 24) as well as in practice [5]. In this paper, we present the UnivMon (short for Univer-sal Monitoring) framework that can simultaneously achieve both generality and high fidelity across a broad spectrum of monitoring tasks [31, 36, 38, 51]. UnivMon builds on and

## SketchLearn

## SIGCOMM '18

## [source]

## SketchLearn: Relieving User Burdens in Approximate Measurement with Automated Statistical Inference

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## 2018 Conference, August 20–25, 2018, Budapest, Hungary. ACM, New York, NY, USA, 17 pages. https://doi.org/10.1145/3230543.3230559

Network measurement is indispensable to modern network management in clouds and data centers. Administrators mea-sure a variety of traffic statistics, such as per-flow frequency, to infer the key behaviors or any unexpected patterns in op-erational networks. They use the measured traffic statistics

to infer the key behaviors or any unexpected patterns in op-erational networks. They use the measuref raffield statistics to form the basis of management operations such as traffic engineering. performance diagonsis, and intrusion preven-tion. Unfortunately, measuring traffic statistics is non-trivial in the face of massive network traffic and large-scale net-work deployment. Error-free measurement requires per-flow tracking [15], yet today's data centre networks can have thousands of concurrent flows in a very small period from Johns [2] down to even Jam [65]. This would require tremen-dous resources for performing per-flow tracking. In view of the resource constraints, many approaches in the literature leverage approximation techniques to trade be-tween resource usage and measurement accuracy. Examples include sampling [9, 37, 64], top-k counting [5, 43, 44, 64], and aketch-based approaches [1, 63, 30, 40, 42, 50], which we collectively refer to as *approximate measurement* approaches. Theriz idea is to construct compassiment with limited re-sources. Approximate measurement that limited re-sources. Approximate measurement that formed building blocks in amy state-of-livent tretwork-wide measurement system(e.g., [32, 46, 51, 56]. Although theoretically source limiting approaches. Although theoretically source limiting approximate mea-surement approaches are inconvenient for as la such applied.

Although theoretically sound, existing approximate mea-surement approaches are inconvenient for use. In such ap-proaches, massive network traffic competes for the limited resources, thereby introducing measurement errors due to *resource conflicts* (e.g., multiple flows are mapped to the same counter in sketch-based measurement). To mitigate errors, sufficient resources must be provisioned in approximate mea-surement based on its theoretical guarantees. Thus, there exists a tight hinding between resource configurations and accuracy parameters. Such tight hinding leads to several prac-tical limitations (see §22 for details): (i) administrators need

ABSTRACT Network measurement is challenged to fulfill stringent re-source requirements in the face of massive network traffic. source requirements in the face of massive network traffic. While approximate measurement on Ir had accuracy for re-source averages, it demunds intensive manual efforts to config-ure the right resource-accuracy traffic-offs in real deposition such uses burdens are caused by how existing approximate measurement approaches inherently deal with resource to a survey of traffic attaictio to fast the key behaviors or at first swhen tracking massive network traffic with limited resources. In payncahes inherently deal with resource to a survey of traffic attaictio to fast the key behaviors or at for the basis of management to form the basis of management for the task of management framework that resolver source confilts by learning their statistical that resolver source confilts the learning the sources of the other that resolver source confilts the learning the sources of the other that resolver source confilts the learning the sources of the sources of the other that resolver source confilts the learning the sources of the source Stetchicaera, a novel sketch-based measurement framework that resolves resource conflicts by learning their statistical properties to eliminate conflicting traffic components. We prototype Sketchicaera on OpenVisich and P4, and our testbed experiments and attress-test simulation show that Sketchicaera accurately and automatically monitors various traffic attastics and effectively supports network-wide mea-surement with limited resources.

CCS CONCEPTS

#### KEYWORDS Sketch: Network measurement

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# SketchLearn combines multiple sketches with elaborate post-processing for flexibility

## SketchLearn: Relieving User Burdens in Approximate Measurement with Automated Statistical Inference

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## ABSTRACT

Network measurement is challenged to fulfill stringent resource requirements in the face of massive network traffic. While approximate measurement can trade accuracy for resource savings, it demands intensive manual efforts to configure the right resource-accuracy trade-offs in real deployment. Such user burdens are caused by how existing approximate measurement approaches inherently deal with resource conflicts when tracking massive network traffic with limited resources. In particular, they tightly couple resource configurations with accuracy parameters, so as to provision sufficient resources to bound the measurement errors. We design SketchLearn, a novel sketch-based measurement framework that resolves resource conflicts by learning their statistical properties to eliminate conflicting traffic components. We prototype SketchLearn on OpenVSwitch and P4, and our testbed experiments and stress-test simulation show that SketchLearn accurately and automatically monitors various traffic statistics and effectively supports network-wide measurement with limited resources.

## CCS CONCEPTS

Networks → Network measurement;

## KEYWORDS

Sketch; Network measurement

## ACM Reference Format:

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## 1 INTRODUCTION

Network measurement is indispensable to modern network management in clouds and data centers. Administrators measure a variety of traffic statistics, such as per-flow frequency, to infer the key behaviors or any unexpected patterns in operational networks. They use the measured traffic statistics to form the basis of management operations such as traffic engineering, performance diagnosis, and intrusion prevention. Unfortunately, measuring traffic statistics is non-trivial in the face of massive network traffic and large-scale network deployment. Error-free measurement requires per-flow tracking [15], yet today's data center networks can have thousands of concurrent flows in a very small period from 50ms [2] down to even 5ms [56]. This would require tremendous resources for performing per-flow tracking.

In view of the resource constraints, many approaches in the literature leverage approximation techniques to trade between resource usage and measurement accuracy. Examples include sampling [9, 37, 64], top-k counting [5, 43, 44, 46], and sketch-based approaches [18, 33, 40, 42, 58], which we collectively refer to as *approximate measurement* approaches. Their idea is to construct compact sub-linear data structures to record traffic statistics, backed by theoretical guarantees on how to achieve accurate measurement with limited resources. Approximate measurement has formed building blocks in many state-of-the-art network-wide measurement systems (e.g., [32, 48, 55, 60, 62, 67]) and is also adopted in Today we'll talk about: important questions,

how 'sketches' answer them,

# limitations of 'sketches',

and my master thesis :)

Sketches compute statistical summaries, favoring elements with **high frequency**.

 $Pr\left[\left|\widehat{x}_{i}-x_{i}\right| \geq \varepsilon \left\|\mathbf{x}_{i}\right\|_{1}\right] \leq \delta$ 

error

*estimation relative to sum* of all elements

Sketches **compute statistical summaries**, favoring elements with **high frequency**.

Let  $\varepsilon = 0.01$ ,  $||\mathbf{x}||_1 = 10000 \quad (\Rightarrow \varepsilon \cdot ||\mathbf{x}||_1 = 100)$ 

Assume two flows  $x_a$ ,  $x_b$ ,

with  $||x_a||_1 = 1000$ ,  $||x_b||_1 = 50$ | Iow frequency high frequency Sketches **compute statistical summaries**, favoring elements with **high frequency**.

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Assume two flows  $x_a$ ,  $x_b$ ,

with  $||x_a||_1 = 1000$ ,  $||x_b||_1 = 50$ 

Error relative to **stream size**: 1%

Sketches **compute statistical summaries**, favoring elements with **high frequency**.

Let  $\varepsilon = 0.01$ ,  $||\mathbf{x}||_1 = 10000$  ( $\Rightarrow \varepsilon \cdot ||\mathbf{x}||_1 = 100$ )

Assume two flows  $x_a$ ,  $x_b$ ,

with  $||x_a||_1 = 1000$ ,  $||x_b||_1 = 50$ 

Error relative to **stream size**: 1% **flow size**: x<sub>a</sub>: 10%, x<sub>b</sub>: 200% Other Problems a Sketch can't handle

causality

patterns

rare things



Regardless of their limitations, sketches provide **trade-offs between resources and error**, and **provable guarantees** to rely on. Today we'll talk about: important questions,

how 'sketches' answer them,

limitations of 'sketches',

and my master thesis :)

# Advanced Topics in Communication Networks Programming Network Data Planes



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